STÖBER

POSIDRIVE® FDS 5000

NEXT GENERATION!

Functional housing design

As part of the STÖBER EMC strategy, all the housings in the POSIDRIVE® FDS 5000 series are made of galvanized sheet steel. They shield against electromagnetic interference and thus increase the units' RFI immunity and reduce interference emission.

The housing incorporates the operator keypad, display, LED indicators, Paramodul and RS232 interface.

The optional field bus modules (CANopen DS-301, PROFIBUS DP-V1, EtherCAT) are easily plugged in from the top.

THE **PURPOSE** DESIGNED **ASYNCHRONOUS** SERVO AXIS

New innovation potential for feed and positioning drives

The versatile and reliable POSIDRIVE® FDS has been further developed to form the 5000 series.

The innovative development approach concentrated on perfect use of the **POSITool software** and the smooth and fast **field bus communication** with different bus systems.

The performance profile of the POSIDRIVE® FDS 5000 is configurable for specific applications.

The practical spectrum of functionalities enables the POSIDRIVE® FDS 5000 to take over complex control tasks

from the higher-level plant or machine control system.

Typical **applications** for POSIDRIVE® FDS 5000 inverters are packaging systems, automation engineering and machine tool manufacture with challenging feed systems and positioning drives.
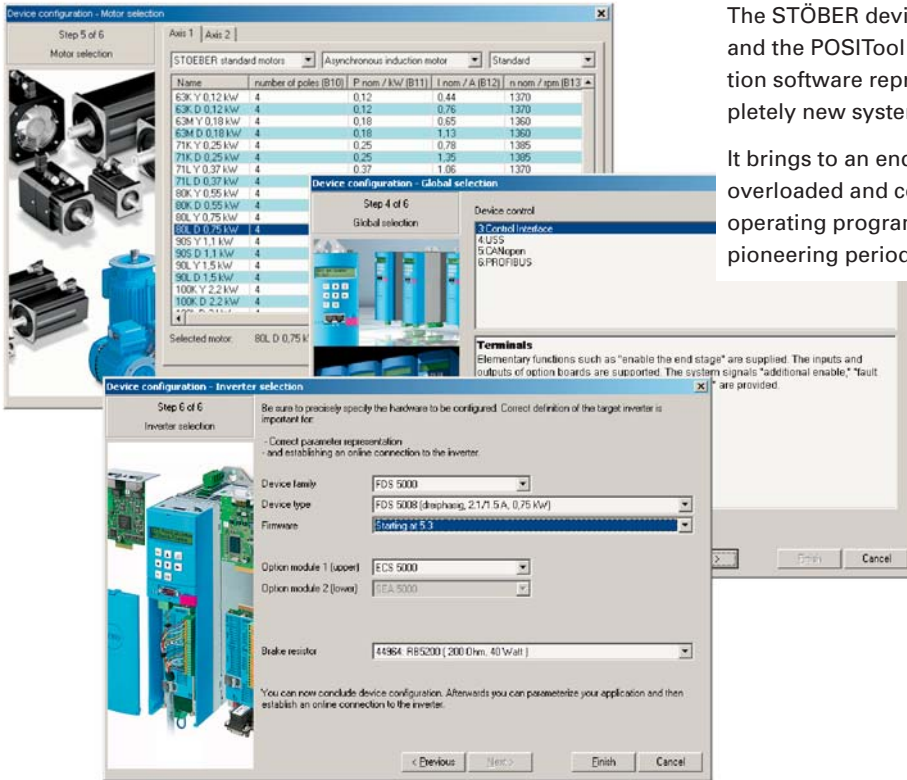
Paramodul

Plug-in memory module for transfer of all program and settings data.

If a POSIDRIVE® FDS 5000 has to be replaced, the existing Paramodul is simply plugged into the new unit to restart operations. The functionality is retained without restriction.
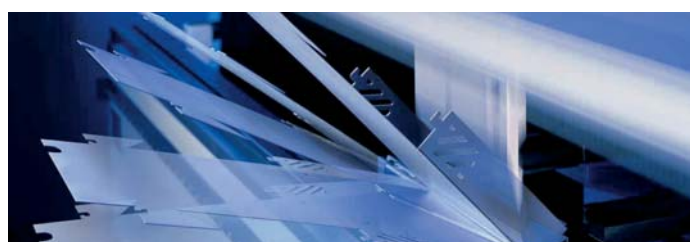
TOWARDS **NEW** GOALS WITH
A NEW SOFTWARE **GENERATION**

The STÖBER device firmware and the POSITool parameterization software represent a completely new system technology.

It brings to an end the era of overloaded and confusing operating programs from the pioneering period of inverters.

POSITool is based on a completely new, modular 3-layer architecture with ergonomic interface design. An applications library with parameterization assistant and an additional flexible graphics programming facility forms a successful bridge between custom-made design and universality.

Encoder interfaces for 2 systems:
HTL incremental encoder
("24V" for MGS system motors)
TTL incremental encoder *(RS422, "5V")*

POSIDRIVE® FDS 5000.
OPTIMIZED FOR **MGS** GEARED MOTORS
FROM 0.37 TO 7.5 kW

The MGS modular geared motor system is based on four gear unit series with high running precision and a variety of equipment options. The power and speed are logically grouped. These factors qualify the MGS system for design of a very specific actuator system.

For operation in VC mode (high dynamics vector control with speed feedback), MGS system motors are fitted with incremental encoders.

POSIDRIVE® FDS 5000 is hardware and software optimized for use with MGS geared motors. They are suitable for operation with all industry standard motors of other manufacturers.

The POSIDRIVE® FDS 5000 offers a choice of 3 different control modes

VC mode – High-dynamic vector control with speed feedback
Inputs for incremental encoder (standard) and digital evaluation. The MGS geared motor becomes a cost-effective 'asynchronous servo axis'.
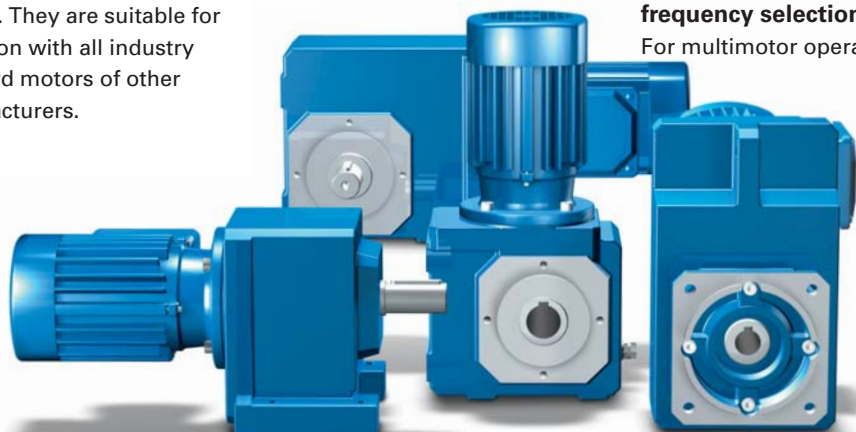
SLVC – Motor control through sensorless vector control
Good dynamic performance and accuracy through vector control without encoder and speed feedback.

V/f – Motor control through frequency selection
For multimotor operation.

MGS system motor
with incremental encoder

MODULAR
SOFTWARE ARCHITECTURE

The high dynamism of electronic development brings about continuous improvements and extending of functions, particularly with frequency inverters. But associated with this is continuously increasing user software complexity. A trend which is in stark contrast to the need for simple and accurate usability.

This conflict has been tackled by STÖBER ANTRIEBSTECHNIK. When developing the completely new firmware and POSITool user software, a logical new strategy was adopted.

Instead of rigidly defined firmware with endless parameter settings, the operator finds a modern, ergonomically designed user interface.

For everyday

To configure a drive, the POSITool user software offers a library with typical preproduced basic applications. Here is a selection:

- Fast reference value
- Comfort reference value
  Speed or torque reference value (selectable)
  3 analog reference values
  16 fixed reference values
  Motorized potentiometer
  PID controller reference value
  Reference values scalable as absolute or percentage value
- Limited position range command positioning
- Endless position range command positioning
- Command positioning with the special POSILatch function. Position measurements can then be taken on external signals (e.g. linear measurements)
- Motion block positioning
- Electronic cam function

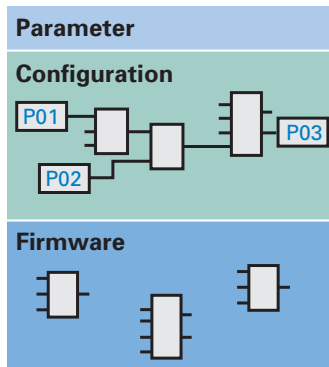The consistent application orientation of the modules is proving extremely effective.

In particular for fast commissioning the comfort reference value ensures flexibly adjustable unit settings.

All parameterization work is supported by assistant functions.

Parameter
Configuration

Scalable software architecture

Other highlights

The software scalability allows optimum adaptation of functionality and response time to the application. The cycle time for reference value processing depends only on the calculation of the activated system modules and the parameters.

Even complex applications can be mapped on the same hardware platform without modifying the firmware.

For experts

The new, user programmable firmware has been upgraded to include a graphics editor layer. A trained user will find a variety of defined function blocks in various libraries. With these basic applications can be modified or given extra functions.

Extra service

For customer-specific creation of a completely new functional structure or comprehensive adaptation of the graphics configuration layer, STÖBER ANTRIEBSTECHNIK offers the service package **TAILOR MADE APPLICATIONS**.

User-friendly system maintenance

The **documentation feature** of the POSITool user software facilitates thorough system maintenance. The fine-tuned settings and operational data of each drive are recorded and documented. The Paramodul is perfect for this task.

The **data** of each individual drive are thus available for system maintenance or further configurations.

With the **diagnostic function**, the cause of a fault can be found quickly with a notebook. The analysis of the 'error data' by POSITool helps service engineers to locate the actual cause quickly. If a drive fails due to overload or damage, the cause can be an undetected problem area elsewhere.

Technical data
POSIDRIVE® FDS 5000

Size
Type
ID (device version/H)
Recommended motor power
Supply voltage
Line fuses
Rated current I_{rated}
I_{max}
Switching frequency
Braking resistor (accessory)
Permissible motor cable length, shielded
Power loss at $I_{outp} = I_{rated}$
Power loss at $I_{outp} = 0A^2$
Conductor cross-section
Dimensions (H x W x D) [mm]
Weight [kg] without packaging
Weight [kg] with packaging

UNCOMPROMISING **INDUSTRIAL** ELECTRONICS

Powerful processor core
32-bit RISC processor
Current controller 250 μs

Control modes
Asynchronous servo motors
(V/f, SLVC, VC)

Encoder interface
Incremental encoder (TTL, HTL)

Serial interface
RS232 with USS protocol

Slot
Communication

Options
CANopen DS-301 (CAN5000)
PROFIBUS DP-V1 (DP5000)
EtherCAT (ECS5000)

I/O Terminal module LEA5000
(8 binary inputs, 8 binary outputs)

Operational reliability
Generously sized power stage for 180 % accelerating current

Thermistor motor protection
Monitoring circuit for up to 3 PTC thermistors

Brake chopper integral
Thermal model monitoring of external resistor for overload

Fan
Temperature controlled

DC link connection
For energy exchange between several inverters

Operator unit
8 keys, changing of parameters, jogging (manual operation) (clear text display and LED indicators)

Paramodul
Plug-in module for power failure safe storage of all application specific data
Data transfer without any further aids

Control electronics supply
DC link power supply unit or power supply unit with connection facility for external +24 V (the control section remains functional even if the supply voltage is switched off)

Ease of installation
All terminals are plug-in type (spring-loaded terminals)
Supply and motor connections in separate places
Twin DC link terminals, facilitates parallel connection
EMC plate for shield connection

ASP 5001
Safe torque off (STO)
Permits safe protection of drives against unexpected starting. TÜV-certified in accordance with EN954-1, cat. 3. (Certification in accordance with EN ISO 13849-1 in preparation)

POSITool Windows Software
Application selection (with assistant)
Parameterization (with assistant)

Manages several inverters (FDS 5000 and MDS 5000) in one installation

Drive optimization with POSI-Scope, oscilloscope function for internal signals (movement visualization), operational data monitoring and diagnosis

PROFIBUS DP-V1 (DP5000)

BG 0				BG 1			
FDS 5007	**FDS 5004**	**FDS 5008**	**FDS 5015**	**FDS 5022**	**FDS 5040**	**FDS 5055**	**FDS 5075**
45962	45961	45963	45964	45965	45966	45967	45968
0.75 kW	0.37 kW	0.75 kW	1.5 kW	2.2 kW	4.0 kW	5.5 kW	7.5 kW
(L1-N) 1 x 230 V +20 %/-40 %,50/60 Hz	(L1-L3) 3 x 400 V +32%/-50% 50 Hz (L1-L3) 3 x 480 V +10%/-58% 60 Hz			(L1-L3) 3 x 400 V +32%/-50% 50 Hz (L1-L3) 3 x 480 V +10%/-58% 60 Hz			
1 x 10 AT	3 x 6 AT	3 x 6 AT	3 x 10 AT	3 x 10 AT	3 x 16 AT	3 x 20 AT	3 x 20 AT
3 x 4.0 A	3 x 1.3 A	3 x 2.1 A	3 x 4.0 A	3 x 5.5 A	3 x 10 A	3 x 12 A	3 x 16 A
180% / 5 sec., 150% / 30 sec.				180% / 5 sec., 150% / 30 sec.			
4 kHz (adjustable up to 16 kHz with derating)				4 kHz (adjustable up to 16 kHz with derating)			
100 Ω: max. 1.6 kW	200 Ω: max. 3.2 kW			100 Ω: max. 6.4 kW		47 Ω: max. 13.6 kW	
100 m, from 50 m with output choke				100 m, from 50 m with output choke			
80 W	50 W	65 W	90 W	110 W	170 W	180 W	200 W
max. 30 W ①				max. 30 W①			
max. 2.5 mm²				max. 4 mm²			
300 x 70 x 157 (175)②				300 x 70 x 242 (260)②			
2.1				3.7			
2.9				4.8			

① *depends on connected option boards and sensors (e.g. encoder)* ② *Depth incl. braking resistor RB5000*

COMPLETE DRIVE –
THE SYSTEM SOLUTION

Drive system solutions based on modular software and hardware are the core area of expertise of the system manufacturer STÖBER ANTRIEBSTECHNIK.

The graphic opposite shows a diagram of the process of target-oriented design of a complete drive unit consisting of:
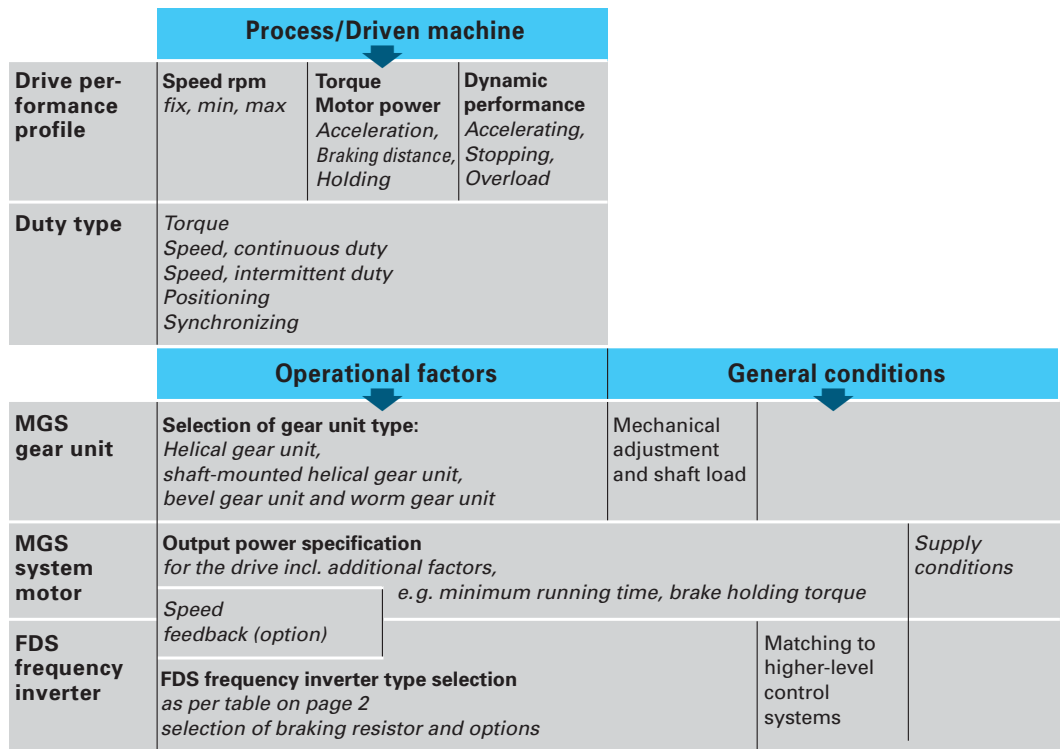
POSIDRIVE® FDS 5000
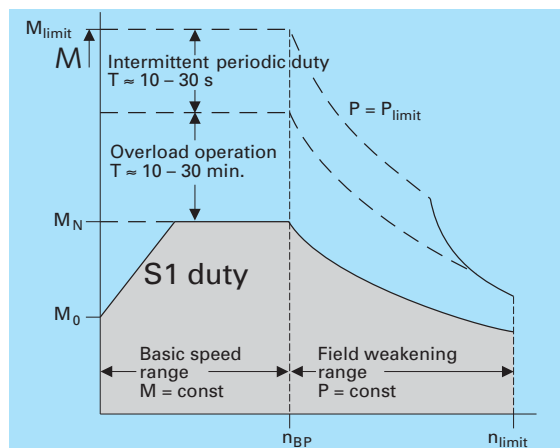frequency inverter and software

MGS gear unit

MGS system motor

The **specification for the components** follows the individual mix of requirements for the process or driven machine.

Process/Driven machine			
Drive per-formance profile	**Speed rpm** *fix, min, max*	**Torque Motor power** *Acceleration, Braking distance, Holding*	**Dynamic performance** *Accelerating, Stopping, Overload*
Duty type	*Torque Speed, continuous duty Speed, intermittent duty Positioning Synchronizing*		

	Operational factors		General conditions	
MGS gear unit	**Selection of gear unit type:** *Helical gear unit, shaft-mounted helical gear unit, bevel gear unit and worm gear unit*		Mechanical adjustment and shaft load	
MGS system motor	**Output power specification** *for the drive incl. additional factors,* *e.g. minimum running time, brake holding torque*			*Supply conditions*
FDS frequency inverter	*Speed feedback (option)*			
	FDS frequency inverter type selection *as per table on page 2* *selection of braking resistor and options*		Matching to higher-level control systems	

Choosing the optimum inverter

Using the breakpoint and with allowance for the power reserves, the right motor can be logically selected.

The diagrams and tables on these pages do not reflect any influencing factors of the selected MGS gear unit. You can find detailed information on these in the MGS catalogue.

Three motor control options

	VC Vector control	SLVC Sensorless vector control	V/f control
Drive type	individual drive	individual drive	multi axis drive
Current rating compared to V/f control	50 %	65 %	100 %
Speed range	1:200 – 1:1000	1:15 – 1:20	1:5 – 1:10
Influence of load variations on speed	none	little	high
Torque limitation	excellent	good	none
Vibration stability	excellent	good	low
Response to critical operating conditions	excellent	good	N/A
Concentricity at low speeds	excellent	good	low
Available torque at zero speed	yes	N/A	N/A
Response to load changes	dynamic	delayed	much delayed
Response to setpoint step changes	dynamic	delayed	much delayed
Incremental encoder	yes	no	no

Speed response of the different motor control types VC, SLVS, V/f

Left: Response to a sudden change in the load torque

Right: Response to a continuous change in the load torque
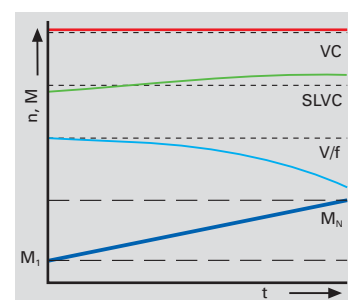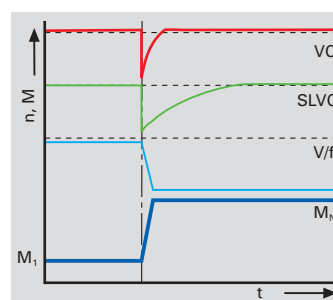
M_1 = starting torque · M_N = motor rated torque · t = time · n = speed

ACCURATE COMMISSIONING

The POSITool Windows user software contains the following functions:

- Application configuration
- Drive parameterization
- Drive programming
- Drive commissioning
- Application commissioning
- Function optimization

The prepared functions and parameters are transferred via the RS232 interface on the device front.
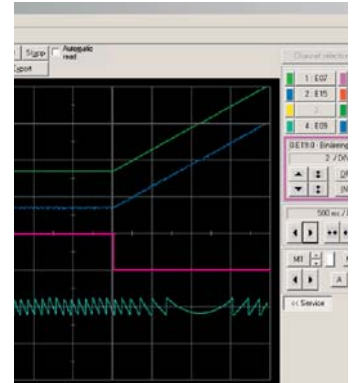
Commissioning the MGS geared motors

The system is commissioned with the help of a notebook and the POSITool device and parameterization software. No software knowledge is required for this. All the adjustments are done interactively.
The POSIDRIVE® FDS 5000 inverter comes supplied with the 'fast reference value' application.

Commissioning the complete application

This can be done either via the connected **PC** or after data transfer via the device **operator panel**.

The **Paramodul** is also suitable for data transfer.

Further parameterization corrections and additions can be made directly. Some knowledge (basic training) is necessary for this task.

Digital drive tuning

The POSIScope software tool reduces trial runs for individual drive optimization to a minimum.

Previous trial and error is replaced by a full diagnosis. In **real time** the procedure is observed, recorded, analyzed and then displayed by **oscillograph** on the PC monitor.

The fine tuning thus obtained results in perfectly adjusted drives. On applications with high specifications, POSIScope can be used for **system maintenance**.

### Programming and user training

The POSITool software assistant supports programming and parameterization for the use of basic applications. However, accurate completion requires appropriate experience or induction by STÖBER training personnel.

The special STÖBER POSITool programming course is part of the "User graphics programming" software option. The aim of the training is to learn to make full use of the universality of the system. Specific control sequences can then be implemented by linking the relevant modules.
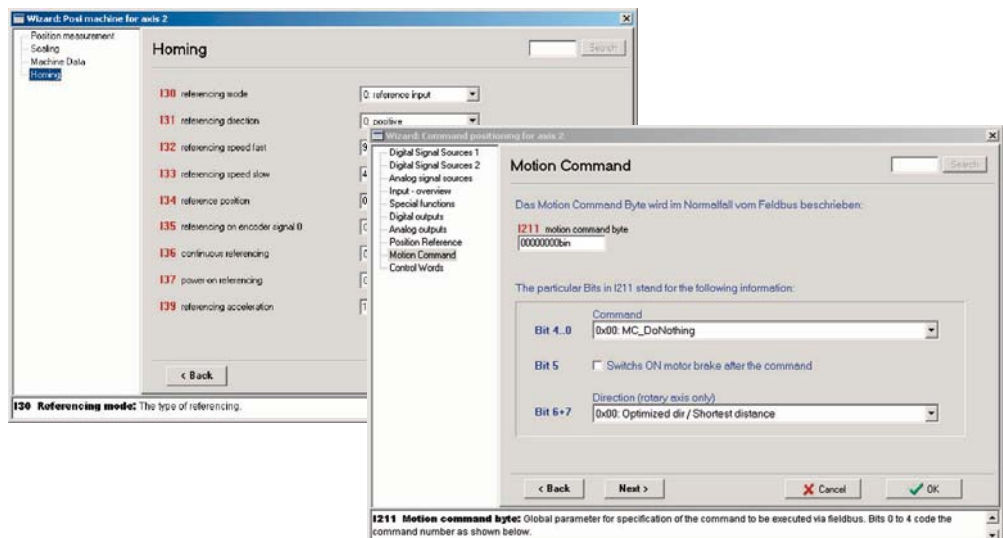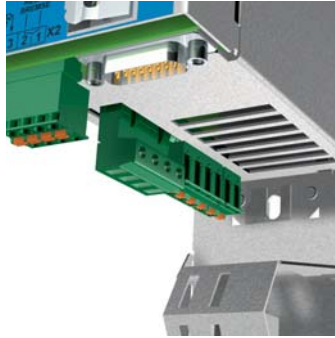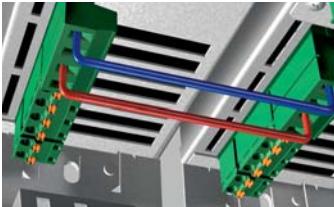
QUICK TO ASSEMBLE

Perfect, practical connection layout
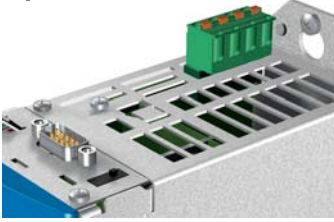
The mains or 24 V supply connection is made 'from above' through a plug-in terminal strip. In the foreground, the optional bus board connection.

Simple DC link connection. Twin DC link terminals for easy parallel connection.

The separate connections for motor, DC link and braking resistor are located on the bottom of the housing. The PTC thermistor and braking relay are also attached here by simple plug-in mounting.

VERY EASY TO USE

Easy data transfer and acceptance with Paramodul.

Display and keypad are integrated allowing for rapid diagnosis, status monitoring, direct parameter access and jogging (manual operation).

Service

The STÖBER service system comprises 36 expert partners in Germany and more than 80 companies in the STÖBER SERVICE NETWORK worldwide.

This full service concept guarantees local expertise and availability when needed.

In general, the service specialists in the Pforzheim factory can be reached at any time via a 24/7 service hotline.

When necessary, urgent action to correct a problem can be put in train immediately.

24/7 service hotline
+49 (0)180 5 786323